# Minimal Variance Hedging for Fractional Brownian Motion * 

Francesca Biagini ${ }^{\dagger} \quad$ Bernt Øksendal $^{\ddagger}$

March 26, 2012


#### Abstract

We discuss the extension to the multi-dimensional case of the Wick-Itô integral with respect to fractional Brownian motion, introduced by [6] in the 1 -dimensional case. We prove a multi-dimensional Itô type isometry for such integrals, which is used in the proof of the multi-dimensional Itô formula. The results are applied to study the problem of minimal variance hedging in a market driven by fractional Brownian motions.


## 1 Introduction

In the following we let $H=\left(H_{1}, H_{2}, \ldots, H_{m}\right)$ be an $m$-dimensional Hurst vector with components $H_{i} \in\left(\frac{1}{2}, 1\right)$ for $i=1,2, \ldots, m$, and we let $B^{(H)}(t)=$ $\left(B_{1}^{(H)}(t), \ldots, B_{m}^{(H)}(t)\right)$ be an $m$-dimensional fractional Brownian motion ( fBm ) with Hurst parameter $H$. This means that $B^{(H)}(t)=B^{(H)}(t, \omega) ; t \in \mathbb{R}$, $\omega \in \Omega$ is a continuous Gaussian stochastic process on a filtered probability space $\left(\Omega, \mathcal{F}_{t}^{(H)}, \mu\right)$ with mean

$$
\begin{equation*}
\mathbb{E}\left[B^{(H)}(t)\right]=0=B^{(H)}(0) \quad \text { for all } t \tag{1}
\end{equation*}
$$

[^0]and covariance
\[

$$
\begin{equation*}
\mathbb{E}\left[B_{i}^{(H)}(s) B_{j}^{(H)}(t)\right]=\frac{1}{2}\left\{|s|^{2 H_{i}}+|t|^{2 H_{i}}-|s-t|^{2 H_{i}}\right\} \delta_{i j} \tag{2}
\end{equation*}
$$

\]

where

$$
\delta_{i j}=\left\{\begin{array}{ll}
0 & \text { if } \quad i \neq j \\
1 & \text { if } \quad i=j ;
\end{array} \quad i \leq i, j \leq m\right.
$$

where $\mathbb{E}=\mathbb{E}_{\mu}$ denotes the expectation with respect to the probability law $\mu$ of $B^{(H)}(\cdot)$.

In other words, $B^{(H)}(t)$ consists of $m$ independent 1-dimensional fractional Brownian motions with Hurst parameters $H_{1}, \ldots, H_{m}$, respectively. If $H_{i}=\frac{1}{2}$ for all $i$, then $B^{(H)}(t)$ coincides with classical Brownian motion $B(t)$. We refer to [11], [13] and [18] for more information about 1dimensional $f B m$. Because of its properties (persistence/antipersistence and self-similarity) $f B m$ has been suggested as a useful mathematical tool in many applications, including finance [10]. For example, these features of $f B m$ seem to appear in the log-returns of stocks [18], in weather derivative models [3] and in electricity prices in a liberated electricity market [20].

In view of this it is of interest to develop a powerful calculus for $f B m$. Unfortunately, $f B m$ is not a semimartingale nor a Markov process (unless $H_{i}=\frac{1}{2}$ for all $i$ ), so these theories cannot be applied to $f B m$. However, if $H_{i}>\frac{1}{2}$ then the paths have zero quadratic variation and it is therefore possible to define a pathwise integral, denoted by

$$
\int_{\mathbb{R}} f(t, \omega) \delta B^{(H)}(t),
$$

by a classical result of Young from 1936. See [12] and the references therein. This integral will obey Stratonovich type (i.e. "deterministic") integration rules. Typically the expectation of such integrals is not 0 and it is known ([12], [15], [16], [19]) that the use of these integrals in finance will give markets with arbitrage, even in the most basic cases. In fact, this unpleasant situation (from a modelling point of view) occurs whenever we use an integration theory with Stratonovich integration rules in the generation of wealth from a portfolio. See e.g. the simple examples of [4] and [19].

Because of this - and for several other reasons - it is natural to try other types of integration with respect to $f B m$. Let $\mathcal{L}_{\phi}^{1,2}$ be the set of (measurable) processes $f(\cdot, \cdot): \mathbb{R} \times \Omega \rightarrow \mathbb{R}$ such that $\|f\|_{\mathcal{L}_{\phi}^{1,2}}<\infty$, where

$$
\begin{equation*}
\|f\|_{\mathcal{L}_{\phi}^{1,2}}^{2}:=\mathbb{E}\left[\int_{\mathbb{R}} \int_{\mathbb{R}} f(s) f(t) \phi(s, t) d s d t+\left(\int_{\mathbb{R}} D_{t}^{\phi} f(t) d t\right)^{2}\right] . \tag{3}
\end{equation*}
$$

## MINIMAL VARIANCE HEDGING FOR FRACTIONAL BROWNIAN MOTION3

In [6] a Wick-Itô type of integral is constructed, denoted by

$$
\int_{\mathbb{R}} f(t, \omega) d B^{(H)}(t)
$$

where $B^{(H)}(t)$ is a 1 -dimensional $f B m$ with $H \in\left(\frac{1}{2}, 1\right)$. This integral exists as an element of $L^{2}(\mu)$ for all (measurable) processes $f(t, \omega)$ such that $\|f\|_{\mathcal{L}_{\phi}^{1,2}}<$ $\infty$. Here, and in the following,

$$
\begin{equation*}
\phi(s, t)=\phi_{H}(s, t)=H(2 H-1)|s-t|^{2 H-2} ; \quad(s, t) \in \mathbb{R}^{2}, \quad \frac{1}{2}<H<1 \tag{4}
\end{equation*}
$$

and

$$
\begin{equation*}
D_{t}^{\phi} F=\int_{\mathbb{R}} \phi(s, t) D_{s} F d s \tag{5}
\end{equation*}
$$

denotes the Malliavin $\phi$-derivative of $F$ (see [6, Definition 3.4]). If $f(t, \omega)$ is a step process of the form

$$
\begin{equation*}
f(t, \omega)=\sum_{i=1}^{n} f_{i}(\omega) \mathcal{X}_{\left[t_{i}, t_{i+1}\right)}(t), \quad \text { where } t_{1}<t_{2}<\cdots<t_{n+1} \tag{6}
\end{equation*}
$$

and $\|f\|_{\mathcal{L}_{\phi}^{1,2}}<\infty$, then the integral is defined by

$$
\begin{equation*}
\int_{\mathbb{R}} f(t, \omega) d B^{(H)}(t)=\sum_{i=1}^{n} f_{i}(\omega) \diamond\left(B^{(H)}\left(t_{i+1}\right)-B^{(H)}\left(t_{i}\right)\right), \tag{7}
\end{equation*}
$$

where $\diamond$ denotes the Wick product. We have the following basic properties of the Wick-Itô integral:
$\mathbb{E}\left[\int_{\mathbb{R}} f(t, \omega) d B^{(H)}(t)\right]=0 \quad$ for all $f \in \mathcal{L}_{\phi}^{1,2}$
$\mathbb{E}\left[\left(\int_{\mathbb{R}} f(t, \omega) d B^{(H)}(t)\right)\left(\int_{\mathbb{R}} g(t, \omega) d B^{(H)}(t)\right)\right]=(f, g)_{\mathcal{L}_{\phi}^{1,2}} \quad$ for all $f, g \in \mathcal{L}_{\phi}^{1,2}$ where
$(f, g)_{\mathcal{L}_{\phi}^{1,2}}=\mathbb{E}\left[\int_{\mathbb{R}} \int_{\mathbb{R}} f(s) g(t) \phi(s, t) d s d t+\left(\int_{\mathbb{R}} D_{t}^{\phi} f(t) d t\right) \cdot\left(\int_{\mathbb{R}} D_{t}^{\phi} g(t) d t\right)\right]$.

See [6] for details and proofs.
This Wick-Itô fractional calculus was subsequently extended to a white noise setting and applied to finance in [9]. Later this white noise theory was generalized to all $H \in(0,1)$ by [7].

All the above papers [6], [9] and [7] only deal with the 1-dimensional case. In Section 2 of this paper we discuss the extension of this integral to the $m$-dimensional case, i.e. we discuss the integral
$\int_{\mathbb{R}} f(t, \omega) d B^{(H)}(t)=\sum_{i=1}^{m} \int_{\mathbb{R}} f_{i}(t, \omega) d B_{i}^{(H)}(t) \quad$ for $f=\left(f_{1}, \ldots, f_{m}\right) \in \mathcal{L}_{\phi}^{1,2}(m)$
where $B^{(H)}(t)=\left(B_{1}^{(H)}(t), \ldots, B_{m}^{(H)}(t)\right)$ is $m$-dimensional $f B m, \phi=\left(\phi_{H_{1}}, \ldots, \phi_{H_{m}}\right)$ and $\mathcal{L}_{\phi}^{1,2}(m)$ is the corresponding class of integrands (see (2.5) below). We prove the $m$-dimensional analogue of the isometry (9), which turns out to have some unexpected features (see Theorem 2.1). By combining the multidimensional fractional Itô formula (Theorem 2.6) with Theorem 2.1 we obtain another fractional Itô isometry (Theorem 2.7). Finally, we end Section 2 by proving a fractional integration by parts formula (Theorem 2.9 and Theorem 2.10).

In Section 3 we apply the above results to study the problem of minimal variance hedging in a (possibly incomplete) market driven by $m$-dimensional $f B m$. Here we use fractional mathematical market model introduced by [9] and by [7]. For classical Brownian motions (and semimartingales) this problem has been studied by many researchers. See for example the survey [17] and the references therein. It turns out that for $f B m$ this problem is even harder than in the classical case and in this paper we concentrate on a special case in order to get more specific results.

## 2 Multi-dimensional Wick-Itô integration with respect to $f B m$

Let $B^{(H)}(t)=\left(B_{1}^{(H)}(t), \ldots, B_{m}^{(H)}(t)\right) ; t \in \mathbb{R}, \omega \in \Omega$ be $m$-dimensional $f B m$ with Hurst vector $H=\left(H_{1}, \ldots, H_{m}\right) \in\left(\frac{1}{2}, 1\right)^{m}$, as in Section 1. Since the $B_{k}^{(H)}(\cdot)$ are independent, we may regard $\Omega$ as a product $\Omega=\Omega_{1} \times \Omega_{2} \times \cdots \times \Omega_{m}$ of identical copies $\Omega_{k}$ of some $\bar{\Omega}$ and write $\omega=\left(\omega_{1}, \ldots, \omega_{m}\right) \in \Omega$.

Let $\mathcal{F}=\mathcal{F}_{\infty}^{(m, H)}$ be the $\sigma$-algebra generated by $\left\{B_{k}^{(H)}(s, \cdot) ; s \in \mathbb{R}, k=\right.$ $1,2, \ldots, m\}$ and let $\mathcal{F}_{t}=\mathcal{F}_{t}^{(m, H)}$ be the $\sigma$-algebra generated by $\left\{B_{k}^{(H)}(s, \cdot) ; 0 \leq\right.$ $s \leq t, k=1,2, \ldots, m\}$. If $F: \Omega \rightarrow \mathbb{R}$ is $\mathcal{F}$-measurable, $1 \leq k \leq m$, we set

$$
\begin{equation*}
D_{k, t}^{\phi} F=\int_{\mathbb{R}} \phi_{k}(s, t) D_{k, t} F d t \quad \text { (if the integral converges) } \tag{11}
\end{equation*}
$$

where

$$
\begin{equation*}
\phi=\left(\phi_{1}, \ldots, \phi_{m}\right) \tag{12}
\end{equation*}
$$

$\phi_{k}(s, t)=\phi_{H_{k}}(s, t)=H_{k}\left(2 H_{k}-1\right)|s-t|^{2 H_{k}-2} ; \quad(s, t) \in \mathbb{R}^{3}, \quad k=1,2, \ldots, m$
and $D_{k, t} F=\frac{\partial F}{\partial \omega_{k}}(t, \omega)$ is the Malliavin derivative of $F$ with respect to $\omega_{k}$, at $(t, \omega)$ (if it exists).

Let $\mathcal{B}=\mathcal{B}(\mathbb{R})$ denote the Borel $\sigma$-algebra on $\mathbb{R}$. Similarly to the 1 dimensional case we can define the multi-dimensional fractional Wick-Itô integral

$$
\begin{equation*}
\int_{\mathbb{R}} f(t, \omega) d B^{(H)}(t)=\sum_{k=1}^{m} \int_{\mathbb{R}} f_{k}(t, \omega) d B_{k}^{(H)}(t) \in L^{2}(\mu) \tag{14}
\end{equation*}
$$

for all $\mathcal{B} \times \mathcal{F}$-measurable processes $f(t, \omega)=\left(f_{1}(t, \omega), \ldots, f_{m}(t, \omega)\right) \in \mathbb{R}^{m}$ such that

$$
\begin{align*}
& \left\|f_{k}\right\|_{\mathcal{L}_{\phi_{k}}^{1,2}}<\infty \quad \text { for all } k=1,2, \ldots, m \text {, where } \\
& \left\|f_{k}\right\|_{\mathcal{L}_{\phi_{k}}^{1,2}}:=\mathbb{E}\left[\int_{\mathbb{R}} \int_{\mathbb{R}} f_{k}(s) f_{k}(t) \phi_{k}(s, t) d s d t+\left(\int_{\mathbb{R}} D_{k, t}^{\phi} f_{k}(t) d t\right)^{2}\right] . \tag{15}
\end{align*}
$$

Denote the set of all such $m$-dimensional processes $f$ by $\mathcal{L}_{\phi}^{1,2}(m)$. As in the 1-dimensional case we obtain the isometries

$$
\begin{equation*}
\mathbb{E}\left[\left(\int_{\mathbb{R}} f_{k} d B_{k}^{(H)}\right)^{2}\right]=\left\|f_{k}\right\|_{\mathcal{L}_{\phi_{k}}^{1,2}} ; \quad k=1,2, \ldots, m \tag{16}
\end{equation*}
$$

This is intuitively clear, since we (by independence of $B_{1}^{(H)}, \ldots, B_{m}^{(H)}$ ) can treat the remaining stochastic variables $\omega_{1}, \ldots, \omega_{k-1}, \omega_{k+1}, \ldots, \omega_{m}$ as parameters and repeat the 1-dimensional approach in the $\omega_{k}$ variable. It is also easy to prove (16) rigorously by writing $f_{k}\left(t, \omega_{1}, \omega_{2}, \ldots, \omega_{m}\right)$ as a limit of sums of products of functions depending only on $\left(t, \omega_{k}\right)$ and only on $\left(\omega_{1}, \ldots, \omega_{k-1}, \omega_{k+1}, \ldots, \omega_{m}\right)$, respectively.

In view of this it is clear that if $f=\left(f_{1}, \ldots, f_{m}\right) \in \mathcal{L}_{\phi}^{1,2}(m)$, then the Wick-Itô integral (14) is well-defined as an element of $L^{2}(\mu)$ and by (16) we have

$$
\begin{equation*}
\left\|\int_{\mathbb{R}} f d B^{(H)}\right\|_{L^{2}(\mu)} \leq \sum_{k=1}^{m}\left\|f_{k}\right\|_{\mathcal{L}_{\phi_{k}}^{1,2}} . \tag{17}
\end{equation*}
$$

It is useful to have an explicit expression for the norm on the left hand side of (17). The following formula is our main result of this section:

Theorem 2.1 (Multi-dimensional fractional Wick-Itô Isometry I) Let $f, g \in \mathcal{L}_{\phi}^{1,2}(m)$. Then

$$
\begin{equation*}
\mathbb{E}\left[\left(\int_{\mathbb{R}} f d B^{(H)}\right) \cdot\left(\int_{\mathbb{R}} g d B^{(H)}\right)\right]=(f, g)_{\mathcal{L}_{\phi}^{1,2}(m)} \tag{18}
\end{equation*}
$$

where
$(f, g)_{\mathcal{L}_{\phi}^{1,2}(m)}$
$=\mathbb{E}\left[\sum_{k=1}^{m} \int_{\mathbb{R}} \int_{\mathbb{R}} f_{k}(s) g_{k}(t) \phi_{k}(s, t) d s d t+\sum_{k, \ell=1}^{m}\left(\int_{\mathbb{R}} D_{\ell, t}^{\phi} f_{k}(t) d t\right) \cdot\left(\int_{\mathbb{R}} D_{k, t}^{\phi} g_{\ell}(t) d t\right)\right]$.

Remark. Note the crossing of the indices $\ell, k$ of the derivatives and the components $f_{k}, g_{\ell}$ in the last terms of the right hand side of (19).

To prove Theorem 2.1 we proceed as in [6], but with the appropriate modifications:

In the 1-dimensional case, let $L_{\phi_{k}}^{2}$ be the set of deterministic functions $\alpha: \mathbb{R} \rightarrow \mathbb{R}$ such that

$$
\begin{equation*}
(\alpha, \alpha)_{\phi_{k}}:=|\alpha|_{\phi_{k}}^{2}:=\int_{\mathbb{R}} \int_{\mathbb{R}} \alpha(s) \alpha(t) \phi_{k}(s, t) d s d t<\infty . \tag{20}
\end{equation*}
$$

If $\alpha \in L_{\phi_{k}}^{2}$ then clearly $\alpha \in \mathcal{L}_{\phi_{k}}^{1,2}$. Hence we can define the Wick (or DoleansDale) exponential

$$
\begin{equation*}
\mathcal{E}(\alpha)=\exp ^{\diamond}\left(\int_{\mathbb{R}} \alpha(t) d B_{k}^{(H)}(t)\right)=\exp \left(\int_{\mathbb{R}} \alpha(t) d B_{k}^{(H)}(t)-\frac{1}{2}|\alpha|_{\phi_{k}}^{2}\right) \tag{21}
\end{equation*}
$$

See e.g. [6, (3.1)] or [9, Example 3.10].
Similarly, in the multidimensional case we put $\phi=\left(\phi_{1}, \ldots, \phi_{m}\right)$ and we let $L_{\phi}^{2}$ be the set of all deterministic functions $\alpha=\left(\alpha_{1}, \ldots, \alpha_{m}\right): \mathbb{R} \rightarrow \mathbb{R}^{m}$ such that $\alpha_{k} \in L_{\phi_{k}}^{2}$ for $k=1, \ldots, m$. If $\alpha \in L_{\phi}^{2}$ we define the corresponding Wick exponential

$$
\begin{align*}
\mathcal{E}(\alpha) & =\exp ^{\diamond}\left(\int_{\mathbb{R}} \alpha(t) d B^{(H)}(t)\right)=\exp ^{\diamond}\left(\sum_{k=1}^{m} \int_{\mathbb{R}} \alpha_{k}(t) d B_{k}^{(H)}(t)\right) \\
& =\exp \left(\sum_{k=1}^{m} \int_{\mathbb{R}} \alpha_{k}(t) d B_{k}^{(H)}(t)-\frac{1}{2}|\alpha|_{\phi}^{2}\right), \tag{22}
\end{align*}
$$

where

$$
\begin{equation*}
|\alpha|_{\phi}^{2}=\sum_{k=1}^{m} \int_{\mathbb{R}} \alpha_{k}(s) \alpha_{k}(t) \phi_{k}(s, t) d s d t=\sum_{k=1}^{m}|\alpha|_{\phi_{k}}^{2} . \tag{23}
\end{equation*}
$$

Let $\mathcal{E}$ be the linear span of all $\mathcal{E}(\alpha) ; \alpha \in L_{\phi}^{2}$. Then we have

Theorem $2.2\left(\left[6\right.\right.$, Theorem 3.1]) $\mathcal{E}$ is a dense subset of $L^{p}(\mathcal{F}, \mu)$, for all $p \geq 1$.
and

Theorem 2.3 ([6, Theorem 3.2]) Let $g_{i}=\left(g_{i 1}, \ldots, g_{i m}\right) \in L_{\phi}^{2}$ for $i=$ $1,2, \ldots, n$ such that

$$
\begin{equation*}
\left|g_{i k}-g_{j k}\right|_{\phi_{k}} \neq 0 \quad \text { if } \quad i \neq j, \quad k=1, \ldots, m \tag{24}
\end{equation*}
$$

Then $\mathcal{E}\left(g_{1}\right), \ldots, \mathcal{E}\left(g_{n}\right)$ are linearly independent in $L^{2}(\mathcal{F}, \mu)$.

If $F \in L^{2}(\mathcal{F}, \mu)$ and $g_{k} \in L_{\phi_{k}}^{2}$ we put, as in [6],

$$
\begin{equation*}
D_{k, \Phi\left(g_{k}\right)} F=\int_{\mathbb{R}} D_{k, t}^{\phi} F \cdot g_{k}(t) d t \tag{25}
\end{equation*}
$$

We list some useful differentiation and Wick product rules. The proofs are similar to the 1-dimensional case and are omitted.

Lemma 2.4 Let $f=\left(f_{1}, \ldots, f_{m}\right) \in L_{\phi}^{2}, g=\left(g_{1}, \ldots, g_{m}\right) \in L_{\phi}^{2}$. Then
(i) $D_{k, \Phi\left(g_{k}\right)}\left(\sum_{i=1}^{m} \int_{\mathbb{R}} f_{i} d B_{i}^{(H)}\right)=\left(f_{k}, g_{k}\right)_{\phi_{k}}, \quad k=1, \ldots, m$, where

$$
\begin{equation*}
\left(f_{k}, g_{k}\right)_{\phi_{k}}=\int_{\mathbb{R}} \int_{\mathbb{R}} f_{k}(s) g_{k}(t) \phi_{k}(s, t) d s d t ; \quad k=1, \ldots, m \tag{26}
\end{equation*}
$$

(ii) $D_{k, s}^{\phi}\left(\sum_{i=1}^{m} \int_{\mathbb{R}} f_{i} d B_{i}^{(H)}\right)=\int_{\mathbb{R}} f_{k}(u) \phi_{k}(s, u) d u ; \quad k=1, \ldots, m$,
(iii) $D_{k, \Phi\left(g_{k}\right)} \mathcal{E}(f)=\mathcal{E}(f) \cdot\left(f_{k}, g_{k}\right)_{\phi_{k}} ; \quad k=1, \ldots, m$,
(iv) $D_{k, s}^{\phi} \mathcal{E}(f)=\mathcal{E}(f) \cdot \int_{\mathbb{R}} f_{k}(u) \phi_{k}(s, u) d u ; \quad k=1, \ldots, m$,
(v) $\mathcal{E}(f) \diamond \mathcal{E}(g)=\mathcal{E}(f+g)$
(vi) $F \diamond \int_{\mathbb{R}} g_{k} d B_{k}^{(H)}=F \cdot \int_{\mathbb{R}} g_{k} d B_{k}^{(H)}-D_{k, \Phi\left(g_{k}\right)} F, \quad k=1, \ldots, m$, provided that $F \in L^{2}(\mathcal{F}, \mu)$ and $D_{k, \Phi\left(g_{k}\right)} F \in L^{2}(\mathcal{F}, \mu)$.
(vii) $\mathbb{E}[\mathcal{E}(f) \cdot \mathcal{E}(g)]=\exp (f, g)_{\phi}$.

We now turn to the multi-dimensional case. We will prove

Lemma 2.5 Suppose $\alpha_{k} \in L_{\phi_{k}}^{2}, \beta_{\ell} \in L_{\phi_{\ell}}^{2}, D_{\ell, \Phi\left(\beta_{\ell}\right)} F \in L^{2}(\mu)$ and $D_{k, \Phi\left(\alpha_{k}\right)} G \in$ $L^{2}(\mu)$. Then

$$
\begin{align*}
& \mathbb{E}\left[\left(F \diamond \int_{\mathbb{R}} \alpha_{k} d B_{k}^{(H)}\right) \cdot\left(G \diamond \int_{\mathbb{R}} \beta_{\ell} d B_{\ell}^{(H)}\right)\right] \\
& \quad=\mathbb{E}\left[\left(D_{\ell, \Phi\left(\beta_{\ell}\right)} F\right) \cdot\left(D_{k, \Phi\left(\alpha_{k}\right)} G\right)+\delta_{k \ell} F G\left(\alpha_{k}, \beta_{k}\right)_{\phi_{k}}\right] \tag{27}
\end{align*}
$$

where

$$
\delta_{k \ell}= \begin{cases}1 & \text { if } k=\ell \\ 0 & \text { otherwise }\end{cases}
$$

Proof. We adapt the argument in [6] to the multi-dimensional case:
First note that by a density argument we may assume that

$$
F=\mathcal{E}(f)=\exp \left\{\int_{\mathbb{R}} f(t) d B^{(H)}(t)-\frac{1}{2}|f|_{\phi}^{2}\right\}
$$

and

$$
G=\mathcal{E}(g)=\exp \left\{\int_{\mathbb{R}} g(t) d B^{(H)}(t)-\frac{1}{2}|g|_{\phi}^{2}\right\},
$$

for some $f \in L_{\phi}^{2}, g \in L_{\phi}^{2}$.
Choose $\delta=\left(\delta_{1}, \ldots, \delta_{m}\right) \in \mathbb{R}^{m}, \gamma=\left(\gamma_{1}, \ldots, \gamma_{m}\right) \in \mathbb{R}^{m}$ and put $\delta \times f=$ $\left(\delta_{1} f_{1}, \ldots, \delta_{m} f_{m}\right)$ and $\gamma \times g=\left(\gamma_{1} g_{1}, \ldots, \gamma_{m} g_{m}\right)$. Then by Lemma 2.4

$$
\begin{align*}
\mathbb{E} & {[(\mathcal{E}(f) \diamond \mathcal{E}(\delta \times \alpha)) \cdot(\mathcal{E}(g) \diamond \mathcal{E}(\gamma \times \beta))] }  \tag{28}\\
& =\mathbb{E}[\mathcal{E}(f+\delta \times \alpha) \cdot \mathcal{E}(g+\gamma \times \beta)]=\exp (f+\delta \times \alpha, g+\gamma \times \beta)_{\phi} \\
& =\exp \left\{\sum_{i=1}^{m} \int_{\mathbb{R}} \int_{\mathbb{R}}\left(f_{i}+\delta_{i} \alpha_{i}\right)(s)\left(g_{i}+\gamma_{i} \beta_{i}\right)(t) \phi_{i}(s, t) d s d t\right\} . \tag{29}
\end{align*}
$$

We now compute the double derivatives

$$
\frac{\partial^{2}}{\partial \delta_{k} \partial \gamma_{\ell}}
$$

of (28) and (29) at $\delta=\gamma=0$. We distinguish between two cases:

Case $1 \quad k \neq \ell$
Then if we differentiate (28) we get

$$
\begin{align*}
\frac{\partial^{2}}{\partial \delta_{k} \partial \gamma_{\ell}} & \mathbb{E}[(\mathcal{E}(f) \diamond \mathcal{E}(\delta \times \alpha)) \cdot(\mathcal{E}(g) \diamond \mathcal{E}(\gamma \times \beta))]_{\delta=\gamma=0} \\
& \left.=\frac{\partial}{\partial \gamma_{\ell}} \mathbb{E}\left[\left(\mathcal{E}(f) \diamond \mathcal{E}(\delta \times \alpha) \diamond \int_{\mathbb{R}} \alpha_{k} d B_{k}^{(H)}\right)\right) \cdot(\mathcal{E}(g) \diamond \mathcal{E}(\gamma \times \beta))\right]_{\delta=\gamma=0} \\
& =\mathbb{E}\left[\left(\mathcal{E}(f) \diamond \int_{\mathbb{R}} \alpha_{k} d B_{k}^{(H)}\right) \cdot\left(\mathcal{E}(g) \diamond \int_{\mathbb{R}} \beta_{\ell} d B_{\ell}^{(H)}\right)\right] . \tag{30}
\end{align*}
$$

On the other hand, if we differentiate (29) we get

$$
\begin{align*}
& \frac{\partial^{2}}{\partial \delta_{k} \partial \gamma_{\ell}}\left[\exp (f+\delta \times \alpha, g+\gamma \times \beta)_{\phi}\right]_{\delta=\gamma=0} \\
& =\frac{\partial}{\partial \gamma_{\ell}}\left[\exp (f+\delta \times \alpha, g+\gamma \times \beta)_{\phi} \cdot \int_{\mathbb{R}} \int_{\mathbb{R}} \alpha_{k}(s)\left(g_{k}+\gamma_{k} \beta_{k}\right)(t) \phi_{k}(s, t) d s d t\right]_{\delta=\gamma=0} \\
& =\exp (f, g)_{\phi} \cdot \int_{\mathbb{R}} \int_{\mathbb{R}} \alpha_{k}(s) g_{k}(t) \phi_{k}(s, t) d s d t \cdot \int_{\mathbb{R}} \int_{\mathbb{R}} \beta_{\ell}(s) f_{\ell}(t) \phi_{\ell}(s, t) d s d t \\
& =\exp (f, g)_{\phi} \cdot\left(\alpha_{k}, g_{k}\right)_{\phi_{k}} \cdot\left(\beta_{\ell}, f_{\ell}\right)_{\phi_{\ell}} \\
& =\mathbb{E}\left[\mathcal{E}(f) \cdot\left(\beta_{\ell}, f_{\ell}\right)_{\phi_{\ell}} \cdot \mathcal{E}(g) \cdot\left(\alpha_{k}, g_{k}\right)_{\phi_{k}}\right] \\
& =\mathbb{E}\left[D_{\ell, \Phi\left(\beta_{\ell}\right)} \mathcal{E}(f) \cdot D_{k, \Phi\left(\alpha_{k}\right)} \mathcal{E}(g)\right] . \tag{31}
\end{align*}
$$

This proves (27) in this case.
Case $2 k=\ell$.
In this case, if we differentiate (28) we get

$$
\begin{align*}
\frac{\partial^{2}}{\partial \delta_{k} \partial \gamma_{k}} & \mathbb{E}[(\mathcal{E}(f) \diamond \mathcal{E}(\delta \times \alpha)) \cdot(\mathcal{E}(g) \diamond \mathcal{E}(\gamma \times \beta))]_{\delta=\gamma=0} \\
& =\frac{\partial}{\partial \gamma_{k}} \mathbb{E}\left[\left(\mathcal{E}(f) \diamond \mathcal{E}(\delta \times \alpha) \diamond \int_{\mathbb{R}} \alpha_{k} d B_{k}^{(H)}\right) \cdot(\mathcal{E}(g) \diamond \mathcal{E}(\gamma \times \beta))\right]_{\delta=\gamma=0} \\
& =\mathbb{E}\left[\left(\mathcal{E}(f) \diamond \int_{\mathbb{R}} \alpha_{k} d B_{k}^{(H)}\right) \cdot\left(\mathcal{E}(g) \diamond \int_{\mathbb{R}} \beta_{k} d B_{k}^{(H)}\right)\right] . \tag{32}
\end{align*}
$$

On the other hand, if we differentiate (29) we get

$$
\begin{align*}
& \frac{\partial^{2}}{\partial \delta_{k} \partial \gamma_{k}}\left[\exp (f+\delta \times \alpha, g+\gamma \times \beta)_{\phi}\right]_{\delta=\gamma=0} \\
& =\frac{\partial}{\partial \gamma_{k}}\left[\exp (f+\delta \times \alpha, g+\gamma \times \beta)_{\phi} \cdot \int_{\mathbb{R}} \int_{\mathbb{R}} \alpha_{k}(s)\left(g_{k}+\gamma_{k} \beta_{k}\right)(t) \phi_{k}(s, t) d s d t\right]_{\delta=\gamma=0} \\
& =\exp (f, g)_{\phi} \cdot\left[\left(\alpha_{k}, g_{k}\right)_{\phi_{k}} \cdot\left(\beta_{k}, f_{k}\right)_{\phi_{k}}+\int_{\mathbb{R}} \int_{\mathbb{R}} \alpha_{k}(s) \beta_{k}(t) \phi_{k}(s, t) d s d t\right] \\
& =\mathbb{E}\left[D_{k, \Phi\left(\beta_{k}\right)} \mathcal{E}(f) \cdot D_{k, \Phi\left(\alpha_{k}\right)} \mathcal{E}(g)+\mathcal{E}(f) \mathcal{E}(g)\left(\alpha_{k}, \beta_{k}\right)_{\phi_{k}}\right] \tag{33}
\end{align*}
$$

This proves (27) also for Case 2 and the proof of Lemma 2.5 is complete.
We are now ready to prove Theorem 2.1:
Proof. We may consider $\int_{\mathbb{R}} f_{k}(t) d B_{k}^{(H)}(t)$ as the limit of sums of the form

$$
\sum_{i=1}^{N} f_{k}\left(t_{i}\right) \diamond\left(B_{k}^{(H)}\left(t_{i+1}\right)-B_{k}^{(H)}\left(t_{i}\right)\right)
$$

when $\Delta t_{i}=t_{i+1}-t_{i} \rightarrow 0, t_{1}<t_{2}<\cdots<t_{N}, N=2,3, \ldots$ Hence $\mathbb{E}\left[\left(\int_{\mathbb{R}} f d B^{(H)}\right)^{2}\right]=\mathbb{E}\left[\left(\sum_{k=1}^{m} \int_{\mathbb{R}} f_{k} d B_{k}^{(H)}\right)^{2}\right]$ is the limit of sums of the form $\sum_{i, j, k, \ell} \mathbb{E}\left[\left(f_{k}\left(t_{i}\right) \diamond\left(B_{k}^{(H)}\left(t_{i+1}\right)-B_{k}^{(H)}\left(t_{i}\right)\right)\right) \cdot\left(f_{\ell}\left(t_{j}\right) \diamond\left(B_{\ell}^{(H)}\left(t_{j+1}\right)-B_{\ell}^{(H)}\left(t_{j}\right)\right)\right]\right.$,
which by Lemma 2.5 is equal to
$\sum_{i, j, k, \ell} \mathbb{E}\left[\left(\int_{t_{i}}^{t_{i+1}} D_{\ell, t}^{\phi} f_{k}\left(t_{i}\right) d t\right) \cdot\left(\int_{t_{j}}^{t_{j+1}} D_{k, t}^{\phi} f_{\ell}\left(t_{j}\right) d t\right)+\delta_{k \ell} \int_{t_{i}}^{t_{i+1}} \int_{t_{j}}^{t_{j+1}} f_{k}\left(t_{i}\right) f_{k}\left(t_{j}\right) \phi_{k}(s, t) d s d t\right]$.
When $\Delta t_{i} \rightarrow 0$ this converges to
$\mathbb{E}\left[\sum_{k, \ell=1}^{m}\left(\int_{\mathbb{R}} D_{\ell, t}^{\phi} f_{k}(t) d t\right) \cdot\left(\int_{\mathbb{R}} D_{k, t}^{\phi} f_{\ell}(t) d t\right)+\sum_{k=1}^{m} \int_{\mathbb{R}} \int_{\mathbb{R}} f_{k}(s) f_{k}(t) \phi_{k}(s, t) d s d t\right]$.
This proves (19) when $f=g$. By polarization the proof of Theorem 2.1 is complete.

## MINIMAL VARIANCE HEDGING FOR FRACTIONAL BROWNIAN MOTION11

Using Theorem 2.1 we can now proceed as in the 1-dimensional case ([6, Theorem 4.3]), with appropriate modifications, and obtain a fractional multi-dimensional Itô formula. We omit the proof.

Theorem 2.6 (The fractional multi-dimensional Itô formula) Let $X(t)=$ $\left(X_{1}(t), \ldots, X_{n}(t)\right)$, with

$$
\begin{align*}
& d X_{i}(t)=\sum_{j=1}^{m} \sigma_{i j}(t, \omega) d B_{j}^{(H)}(t) ; \\
& \quad \text { where } \sigma_{i}=\left(\sigma_{i 1}, \ldots, \sigma_{i m}\right) \in \mathcal{L}_{\phi}^{1,2}(m) ; \quad 1 \leq i \leq n . \tag{35}
\end{align*}
$$

Suppose that for all $j=1, \ldots, m$ there exists $\theta_{j}>1-H_{j}$ such that

$$
\begin{equation*}
\sup _{i} \mathbb{E}\left[\left(\sigma_{i j}(u)-\sigma_{i j}(v)\right)^{2}\right] \leq C|u-v|^{\theta_{j}} \quad \text { if }|u-v|<\delta \tag{36}
\end{equation*}
$$

where $\delta>0$ is a constant. Moreover, suppose that

$$
\begin{equation*}
\lim _{\substack{0 u, u \leq t \\|u-v| \rightarrow 0}}\left\{\sup _{i, j, k} \mathbb{E}\left[\left(D_{k, u}^{\phi}\left\{\sigma_{i j}(u)-\sigma_{i j}(v)\right\}\right)^{2}\right]=0 .\right. \tag{37}
\end{equation*}
$$

Let $f \in C^{1,2}\left(\mathbb{R} \times \mathbb{R}^{n}\right)$ with bounded second order derivatives with respect to $x$. Then, for $t>0$,

$$
\begin{align*}
& f(t, X(t))=f(0, X(0))+\int_{0}^{t} \frac{\partial f}{\partial s}(s, X(s)) d s+\int_{0}^{t} \sum_{i=1}^{n} \frac{\partial f}{\partial x_{i}}(s, X(s)) d X_{i}(s) \\
& \quad+\int_{0}^{t}\left\{\sum_{i, j=1}^{m} \frac{\partial^{2} f}{\partial x_{i} \partial x_{j}}(s, X(s)) \sum_{k=1}^{m} \sigma_{i k}(s) D_{k, s}^{\phi}\left(X_{j}(s)\right)\right\} d s  \tag{38}\\
& \quad=f(0, X(0))+\int_{0}^{t} \frac{\partial f}{\partial s}(s, X(s)) d s+\sum_{j=1}^{m} \int_{0}^{t}\left[\sum_{i=1}^{n} \frac{\partial f}{\partial x_{i}}(s, X(s)) \sigma_{i j}(s, \omega)\right] d B_{j}^{(H)}(s) \\
& \quad+\int_{0}^{t} \operatorname{Tr}\left[\Lambda^{T}(s) f_{x x}(s, X(s))\right] d s \tag{39}
\end{align*}
$$

Here $\Lambda=\left[\Lambda_{i j}\right] \in \mathbb{R}^{n \times m}$ with

$$
\begin{align*}
& \Lambda_{i j}(s)=\sum_{k=1}^{m} \sigma_{i k} D_{k, s}^{\phi}\left(X_{j}(s)\right) ; \quad 1 \leq i \leq n, \quad 1 \leq j \leq m,  \tag{40}\\
& f_{x x}=\left[\frac{\partial^{2} f}{\partial x_{i} \partial x_{j}}\right]_{1 \leq i, j \leq n} \in \mathbb{R}^{n \times n} \tag{41}
\end{align*}
$$

and $(\cdot)^{T}$ denotes matrix transposed, $\operatorname{Tr}[\cdot]$ denotes matrix trace.

If we combine Theorem 2.6 with Theorem 2.1 we get the following result, which also may be regarded as a fractional Itô isometry:

Theorem 2.7 (Fractional Itô isometry II) Suppose $f=\left(f_{1}, \ldots, f_{m}\right) \in$ $\mathcal{L}_{\phi}^{1,2}(m)$. Then, for $T>0$,

$$
\begin{align*}
\mathbb{E} & {\left[\left(\int_{0}^{T} D_{\ell, t}^{\phi} f_{k}(t) d t\right) \cdot\left(\int_{0}^{T} D_{k, t}^{\phi} f_{\ell}(t) d t\right)\right] } \\
& =\mathbb{E}\left[\int_{0}^{T}\left\{f_{k}(t) \int_{0}^{t} D_{k, t}^{\phi} f_{\ell}(s) d B_{\ell}^{(H)}(s)+f_{\ell}(t) \int_{0}^{T} D_{\ell, t}^{\phi} f_{k}(s) d B_{k}^{(H)}(s)\right\} d t\right] \tag{42}
\end{align*}
$$

Proof. By the Itô formula (Theorem 2.6) we have

$$
\begin{align*}
\mathbb{E} & {\left[\left(\int_{0}^{T} f_{k} d B_{k}^{(H)}\right) \cdot\left(\int_{0}^{T} f_{\ell} d B_{\ell}^{(H)}\right)\right] } \\
& =\mathbb{E}\left[\int_{0}^{T}\left\{f_{k}(t) D_{k, t}^{\phi}\left(\int_{0}^{t} f_{\ell}(s) d B_{\ell}^{(H)}(s)\right)+f_{k}(t) D_{\ell, t}^{\phi}\left(\int_{0}^{t} f_{k}(s) d B_{k}^{(H)}(s)\right)\right\} d t\right] \\
& =\mathbb{E}\left[\int_{0}^{T}\left\{f_{k}(t) \int_{0}^{t} D_{k, t}^{\phi} f_{\ell}(s) d B_{\ell}^{(H)}(s)+f_{\ell}(t) \int_{0}^{t} D_{\ell, t}^{\phi} f_{k}(s) d B_{k}^{(H)}(s)\right\} d t\right] \\
& +\delta_{k \ell} \mathbb{E}\left[\int_{0}^{T} \int_{0}^{t}\left\{f_{k}(t) f_{k}(s)+f_{\ell}(t) f_{k}(s)\right\} \phi_{k}(s, t) d s d t\right], \tag{43}
\end{align*}
$$

where we have used that, for $u>0$,

$$
\begin{equation*}
D_{k, t}^{\phi}\left(\int_{0}^{u} f_{\ell}(s) d B_{\ell}^{(H)}(s)\right)=\int_{0}^{u} D_{k, t}^{\phi} f_{\ell}(s) d B_{\ell}^{(H)}(s)+\delta_{k \ell} \int_{0}^{u} f_{k}(s) \phi_{k}(t, s) d s \tag{44}
\end{equation*}
$$

(See [6, Theorem 4.2].)
On the other hand, the Itô isometry (Theorem 2.1) gives that

$$
\begin{align*}
& \mathbb{E}\left[\left(\int_{0}^{T} f_{k} d B_{k}^{(H)}\right) \cdot\left(\int_{0}^{T} f_{\ell} d B_{\ell}^{(H)}\right)\right] \\
& \quad=\mathbb{E}\left[\left(\int_{0}^{T} D_{\ell, t}^{\phi} f_{k}(t) d t\right) \cdot\left(\int_{0}^{T} D_{k, t}^{\phi} f_{\ell}(t) d t\right)+\delta_{k \ell}\left|f_{k}\right|_{\phi_{k}}^{2}\right] . \tag{45}
\end{align*}
$$

Comparing (43) and (45) we get Theorem 2.7.

We end this section by proving a fractional integration by parts formula. First we recall

Theorem 2.8 (Fractional Girsanov formula) Suppose $\gamma=\left(\gamma_{1}, \ldots, \gamma_{m}\right) \in$ $\left(L^{2}(\mathbb{R})\right)^{m}$ and $\hat{\gamma}=\left(\hat{\gamma}_{1}, \ldots, \hat{\gamma}_{m}\right) \in L_{\phi}^{2}$ are related by

$$
\begin{equation*}
\gamma_{k}(t)=\int_{\mathbb{R}} \hat{\gamma}_{k}(s) \phi_{k}(s, t) d s ; \quad t \in \mathbb{R}, \quad k=1, \ldots, m \tag{46}
\end{equation*}
$$

Let $G \in L^{2}(\mu)$. Then

$$
\begin{equation*}
\mathbb{E}[G(\omega+\gamma)]=\mathbb{E}\left[G(\omega) \exp ^{\diamond}(\langle\omega, \hat{\gamma}\rangle)\right]=\mathbb{E}\left[G(\omega) \mathcal{E}\left(\int_{\mathbb{R}} \hat{\gamma} d B^{(H)}\right)\right] . \tag{47}
\end{equation*}
$$

For a proof in the 1-dimensional case see e.g. [9, Theorem 3.16]. The proof in the multi-dimensional case is similar.

If $F \in L^{2}(\mu)$ and $\gamma=\left(\gamma_{1}, \ldots, \gamma_{m}\right) \in\left(L^{2}(\mathbb{R})\right)^{m}$ the directional derivative of $F$ in the direction $\gamma$ is defined by

$$
\begin{equation*}
D_{\gamma} F(\omega)=\lim _{\varepsilon \rightarrow 0} \frac{F(\omega+\varepsilon \gamma)-F(\omega)}{\varepsilon} \tag{48}
\end{equation*}
$$

provided the limit exists in $L^{2}(\mu)$. We say that $F$ is differentiable if there exists a process $D_{t} F(\omega)=\left(D_{1, t} F(\omega), \ldots, D_{m, t} F(\omega)\right)$ such that $D_{k, t} F(\omega) \in$ $L^{2}(d \mu \otimes d t)$ for all $k=1, \ldots, m$ and

$$
\begin{equation*}
D_{\gamma} F(\omega)=\int_{\mathbb{R}} D_{t} F(\omega) \cdot \gamma(t) d t \quad \text { for all } \gamma \in\left(L^{2}(\mathbb{R})\right)^{m} \tag{49}
\end{equation*}
$$

Theorem 2.9 (Fractional integration by parts I) Let $F, G \in L^{2}(\mu), \gamma \in$ $\left(L^{2}(\mathbb{R})\right)^{m}$ and assume that the directional derivatives $D_{\gamma} F, D_{\gamma} G$ exist. Then

$$
\begin{equation*}
\mathbb{E}\left[D_{\gamma} F \cdot G\right]=\mathbb{E}\left[F \cdot G \cdot \int_{\mathbb{R}} \hat{\gamma} d B^{(H)}\right]-\mathbb{E}\left[F \cdot D_{\gamma} G\right] \tag{50}
\end{equation*}
$$

Proof. By Theorem 2.8 we have, for all $\varepsilon>0$,

$$
\mathbb{E}[F(\omega+\varepsilon \gamma) G(\omega)]=\mathbb{E}\left[F(\omega) G(\omega-\varepsilon \gamma) \exp ^{\diamond}(\varepsilon\langle\omega, \hat{\gamma}\rangle)\right]
$$

Hence

$$
\begin{aligned}
\mathbb{E}\left[D_{\gamma} F \cdot G\right] & =\mathbb{E}\left[\lim _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon}\{F(\omega+\varepsilon \gamma)-F(\omega)\} G(\omega)\right] \\
& =\mathbb{E}\left[\lim _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon}\left\{F(\omega)\left[G(\omega-\varepsilon \gamma) \exp ^{\diamond}(\varepsilon\langle\omega, \hat{\gamma}\rangle)-G(\omega)\right]\right\}\right] \\
& =\mathbb{E}\left[F(\omega) \frac{d}{d \varepsilon}\left\{G(\omega-\varepsilon \gamma) \exp \left(\varepsilon \int_{\mathbb{R}} \hat{\gamma} d B^{(H)}-\frac{1}{2} \varepsilon^{2}|\hat{\gamma}|_{\phi}^{2}\right)\right\}_{\varepsilon=0}\right] \\
& =\mathbb{E}\left[F(\omega) G(\omega) \int_{\mathbb{R}} \hat{\gamma} d B^{(H)}\right]-\mathbb{E}\left[F(\omega) D_{\gamma} G(\omega)\right]
\end{aligned}
$$

We now apply the above to the fractional gradient

$$
\begin{equation*}
D_{t}^{\phi} F=\int_{\mathbb{R}} D_{s} F \cdot \phi(s, t) d s=\sum_{k=1}^{m} \int_{\mathbb{R}} D_{k, s} F \cdot \phi_{k}(s, t) d s=D_{\phi} F(\omega) \tag{51}
\end{equation*}
$$

Theorem 2.10 (Fractional integration by parts II) Suppose $F, G \in L^{2}(\mu)$ are differentiable, with fractional gradients $D_{t}^{\phi} F, D_{t}^{\phi} G$. Then for each $t \in \mathbb{R}$, $k \in\{1, \ldots, m\}$ we have

$$
\begin{equation*}
\mathbb{E}\left[D_{k, t}^{\phi} F \cdot G\right]=\mathbb{E}\left[F \cdot G \cdot B_{k}^{(H)}(t)\right]-\mathbb{E}\left[F \cdot D_{k, t}^{\phi} G\right] . \tag{52}
\end{equation*}
$$

Proof. Choose a sequence $\hat{\gamma}_{k}^{(j)} \in L_{\phi_{k}}^{2} ; j=1,2, \ldots$, such that $\lim _{j \rightarrow \infty} \hat{\gamma}_{k}^{(j)}=$ $\delta_{t}(\cdot)$ (the point mass at $t$ ), in the sense that if we define

$$
\phi_{k}^{(j)}(s)=\int_{\mathbb{R}} \hat{\gamma}_{k}^{(j)} \phi_{k}(s, r) d r
$$

then $\phi_{k}^{(j)}(\cdot) \rightarrow \phi_{k}(\cdot, t)$ in $L^{2}(\mathbb{R})$. Then by Theorem 2.9

$$
\begin{aligned}
\mathbb{E}\left[D_{k, t}^{\phi} F \cdot G\right] & =\mathbb{E}\left[\lim _{j \rightarrow \infty} D_{\phi_{k}^{(j)}} F \cdot G\right]=\lim _{j \rightarrow \infty} \mathbb{E}\left[D_{\phi_{k}^{(j)}} F \cdot G\right] \\
& =\lim _{j \rightarrow \infty} \mathbb{E}\left[F \cdot G \cdot \int_{\mathbb{R}} \hat{\gamma}^{(j)} d B^{(H)}\right]-\mathbb{E}\left[F \cdot D_{\phi_{k}^{(j)}} G\right] \\
& =\mathbb{E}\left[F \cdot G \cdot B_{k}^{(H)}(t)\right]-\mathbb{E}\left[F \cdot D_{k, t} G\right] .
\end{aligned}
$$

## 3 Application to minimal variance hedging

Consider the multidimensional version of the fractional mathematical market model introduced by [9] and by [7], consisting of $n+1$ independent fractional

Brownian motions $B_{1}^{(H)}(t), \ldots, B_{m}^{(H)}(t)$ with Hurst coefficients $H_{1}, \ldots, H_{m}$ respectively $\left(\frac{1}{2}<H_{i}<1\right)$, as follows:
(bond price) $\quad d S_{0}(t)=r(t, \omega) d t ; \quad S_{0}(0)=s_{0}, \quad 0 \leq t \leq T$
(stock prices) $\quad d S_{i}(t)=\mu_{i}(t, \omega) d t+\sum_{j=1}^{m} \sigma_{i j}(t, \omega) d B_{j}^{(H)}(t) ; \quad S_{i}(0)=s_{i}$,

$$
\begin{equation*}
i=1, \ldots, n, \quad 0 \leq t \leq T \tag{54}
\end{equation*}
$$

Here $r(t, \omega), \mu_{i}(t, \omega)$ and $\sigma_{i j}(t, w)$ are $\mathcal{F}_{t}^{(H)}$-adapted processes satisfying reasonable growth conditions. We refer to [7], [9], [14] and [21] for a general discussion of such markets.

We say that $g=\left(g_{1}, \ldots, g_{m}\right)$ is an admissible portfolio if $g(t)$ is $\mathcal{F}_{t}^{(H)}$ adapted, $g \sigma \in \mathcal{L}_{\phi}^{1,2}(m)$ and $\mathbb{E}\left[\int_{0}^{T} \sum_{i=1}^{n}\left|g_{i}(t) \mu_{i}(t)\right| d t\right]<\infty$. Here we denote by $\sigma$ the volatility matrix $[\sigma]_{i, j}(\cdot)=\sigma_{i j}(\cdot)$. Suppose we are only allowed to trade in some, say $k$, of the securities $S_{0}, \ldots, S_{n}$. Let $\mathcal{K}$ be the set of $i \in$ $\{1, \ldots, n\}$ such that trading in $S_{i}$ is allowed. Then, according to our model, the wealth hedged by an initial value $z \in \mathbb{R}$ and an admissible portfolio $g(t)=\left(g_{i}(t, \omega)\right)_{i \in \mathcal{K}} \in \mathbb{R}^{k}$ up to time $t$ is

$$
\begin{equation*}
V(t)=V_{z}^{g}(t)=z+\sum_{i \in \mathcal{K}} \int_{0}^{t} g_{i}(u) d S_{i}(u) ; \quad 0 \leq t \leq T . \tag{55}
\end{equation*}
$$

Now let $F(\omega)$ be a $T$-claim, i.e. an $\mathcal{F}_{T}^{(H)}$-measurable random variable in $L^{2}(\mu)$.

The minimal variance hedging problem is to find a $z^{*} \in \mathbb{R}$ and an admissible portfolio $g^{*}$ such that

$$
\begin{equation*}
\mathbb{E}\left[\left(F-V_{z^{*}}^{g^{*}}(T)\right)^{2}\right]=\inf _{z, g} \mathbb{E}\left[\left(F-V_{z}^{g}(T)\right)^{2}\right] . \tag{56}
\end{equation*}
$$

This is a difficult problem even in the classical Brownian motion setting. See e.g. [8], [17] and the references therein. For a recent general martingale approach see [5]. For fractional Brownian motion markets a special case is solved in [1] by using optimal control theory.

Here we will discuss the two-dimensional case only, and we will simply assume that

$$
d S_{0}(t)=0, \quad d S_{1}(t)=d B_{1}^{(H)}(t) \quad \text { and } \quad d S_{2}(t)=d B_{2}^{(H)}(t) .
$$

Assume that only trading in $S_{0}$ and $S_{1}$ is allowed. Then the problem is to minimize

$$
\begin{equation*}
J\left(z, g_{1}\right)=\mathbb{E}\left[\left(F-\left(z+\int_{0}^{T} g_{1} d S_{1}\right)\right)^{2}\right] \tag{57}
\end{equation*}
$$

over all $z \in \mathbb{R}$ and all admissible portfolios $g_{1}$.
By the fractional Clark-Haussmann-Ocone formula ([9, Theorem 4.15]) we can write

$$
\begin{equation*}
F(\omega)=\mathbb{E}[F]+\int_{0}^{T} f_{1}(t) d B_{1}^{(H)}(t)+\int_{0}^{T} f_{2}(t) d B_{2}^{(H)}(t) \tag{58}
\end{equation*}
$$

where

$$
f_{i}(t)=\widetilde{\mathbb{E}}\left[D_{i, t} F \mid \mathcal{F}_{t}^{(H)}\right] ; \quad i=1,2 .
$$

Substituting this into (57) we get, by (8),

$$
\begin{align*}
J\left(z, g_{1}\right) & =\mathbb{E}\left[\left(\mathbb{E}[F]-z+\int_{0}^{T}\left(f_{1}-g_{1}\right) d B_{1}^{(H)}+\int_{0}^{T} f_{2} d B_{2}^{(H)}\right)^{2}\right] \\
& =(\mathbb{E}[F]-z)^{2}+\mathbb{E}\left[\left(\int_{0}^{T}\left(f_{1}-g_{1}\right) d B_{1}^{(H)}+\int_{0}^{T} f_{2} d B_{2}^{(H)}\right)^{2}\right] . \tag{59}
\end{align*}
$$

Hence it is optimal to choose $z=z^{*}:=\mathbb{E}[F]$. The remaining problem is therefore to minimize

$$
\begin{equation*}
J_{0}\left(g_{1}\right)=\mathbb{E}\left[\left(\int_{0}^{T}\left(f_{1}-g_{1}\right) d B_{1}^{(H)}+\int_{0}^{T} f_{2} d B_{2}^{(H)}\right)^{2}\right] \tag{60}
\end{equation*}
$$

From now on we assume that $f_{1} \in \mathcal{L}_{\phi_{i}}^{1,2}$ for $i=1,2$. By a Hilbert space argument on $L^{2}(\mu)$ we see that $g_{1}^{*}$ minimizes (60) if and only if

$$
\mathbb{E}\left[\left(\int_{0}^{T}\left(f_{1}-g_{1}\right) d B_{1}^{(H)}+\int_{0}^{T} f_{2} d B_{2}^{(H)}\right) \cdot\left(\int_{0}^{T} \gamma d B_{1}^{(H)}\right)\right]=0
$$

By Theorem 2.1 (61) is equivalent to

$$
\begin{align*}
& \mathbb{E}\left[\int_{0}^{T} \int_{0}^{T}\left(f_{1}(t)-g_{1}(t)\right) \gamma(s) \phi_{1}(s, t) d s d t+\left(\int_{0}^{T} D_{1, t}^{\phi}\left(f_{1}(t)-g_{1}(t)\right) d t\right)\left(\int_{0}^{T} D_{1, t}^{\phi} \gamma(t) d t\right)\right. \\
& \left.\quad+\left(\int_{0}^{T} D_{1, t}^{\phi} f_{2}(t) d t\right) \cdot\left(\int_{0}^{T} D_{2, t}^{\phi} \gamma(t) d t\right)\right] \\
& \quad=0 \quad \text { for all adapted } \gamma \in \mathcal{L}_{\phi}^{1,2} . \tag{62}
\end{align*}
$$

From this we immediately deduce

Proposition 3.1 The portfolio

$$
g_{1}(t)=g_{1}^{*}(t):=f_{1}(t)
$$

minimizes (60) if and only if

$$
\begin{equation*}
\int_{0}^{T} D_{1, t}^{\phi} f_{2}(t) d t=0 \quad \text { a.s. } \tag{63}
\end{equation*}
$$

This result is surprising in view of the corresponding situation for classical Brownian motion, when it is always optimal to choose $g_{1}(t)=g_{1}^{*}(t)=f_{1}(t)$.

We also get
Proposition 3.2 Suppose $g_{1}^{*}(t)$ minimizes (60). Then

$$
\begin{equation*}
\mathbb{E}\left[\int_{0}^{T}\left(f_{1}(t)-g_{1}^{*}(t)\right) d t\right]=0 \tag{64}
\end{equation*}
$$

Proof. This follows by choosing $\gamma(t)$ deterministic in (62).
Now assume that $D_{1, t}^{\phi}\left(f_{1}(t)\right)$ and $D_{1, t}^{\phi}\left(g_{1}(t)\right)$ are differentiable with respect to $D_{1, s}^{\phi}$ and that $D_{1, t}^{\phi} f_{2}(t)$ is differentiable with respect to $D_{2, s}^{\phi}$ for all $s \in[0, T]$. Then we can use integration by parts (Theorem 2.10) to rewrite equation (62) as follows:

$$
\begin{align*}
\mathbb{E}\left[\int_{0}^{T}\right. & \int_{0}^{T}\left\{\left(f_{1}(t)-g_{1}(t)\right) \gamma(s) \phi_{1}(s, t)+D_{1, t}^{\phi}\left(f_{1}(t)-g_{1}(t)\right) \cdot D_{1, s}^{\phi} \gamma(s)\right. \\
& \left.\left.\quad+D_{1, t}^{\phi} f_{2}(t) \cdot D_{2, s}^{\phi} \gamma(s)\right\} d s d t\right] \\
= & \int_{0}^{T} \int_{0}^{T} \mathbb{E}\left[\left(f_{1}(t)-g_{1}(t)\right) \phi_{1}(s, t) \gamma(s)+D_{1, t}^{\phi}\left(f_{1}(t)-g_{1}(t)\right) \gamma(s) B_{1}^{(H)}(s)\right. \\
& \quad-D_{1, s}^{\phi} D_{1, t}^{\phi}\left(f_{1}(t)-g_{1}(t)\right) \gamma(s)+D_{1, t}^{\phi} f_{2}(t) \gamma(s) B_{2}^{(H)}(s) \\
& \left.\quad-D_{2, s}^{\phi} D_{1, t}^{\phi} f_{2}(t) \gamma(s)\right] d s d t \\
= & \mathbb{E}\left[\int_{0}^{T} K(s) \gamma(s) d s\right]=0 \tag{65}
\end{align*}
$$

## MINIMAL VARIANCE HEDGING FOR FRACTIONAL BROWNIAN MOTION18

where

$$
\begin{equation*}
K(s)=\int_{0}^{T} G(s, t) d t \tag{66}
\end{equation*}
$$

with

$$
\begin{align*}
G(s, t) & =\left(f_{1}(t)-g_{1}(t)\right) \phi_{1}(s, t)+D_{1, t}^{\phi}\left(f_{1}(t)-g_{1}(t)\right) B_{1}^{(H)}(s) \\
& -D_{1, s}^{\phi} D_{1, t}^{\phi}\left(f_{1}(t)-g_{1}(t)\right)+D_{1, t}^{\phi} f_{2}(t) B_{2}^{(H)}(s)-D_{2, s}^{\phi} D_{1, t}^{\phi} f_{2}(t) . \tag{67}
\end{align*}
$$

Since $\gamma(s)$ is $\mathcal{F}_{s}^{(H)}$-measurable we get from (65) that

$$
\begin{align*}
0 & =\int_{0}^{T} \mathbb{E}[K(s) \gamma(s)] d s=\int_{0}^{T} \mathbb{E}\left[\mathbb{E}\left[K(s) \gamma(s) \mid \mathcal{F}_{s}^{(H)}\right]\right] d s \\
& =\int_{0}^{T} \mathbb{E}\left[\gamma(s) \mathbb{E}\left[K(s) \mid \mathcal{F}_{s}^{(H)}\right]\right] d s=\mathbb{E}\left[\int_{0}^{T} \mathbb{E}\left[K(s) \mid \mathcal{F}_{s}^{(H)}\right] \gamma(s) d s\right] . \tag{68}
\end{align*}
$$

Since this holds for all adapted $\gamma \in \mathcal{L}_{\phi}^{1,2}$ we conclude that

$$
\begin{equation*}
\mathbb{E}\left[K(s) \mid \mathcal{F}_{s}^{(H)}\right]=0 \quad \text { for a.a. }(s, \omega) . \tag{69}
\end{equation*}
$$

or, using (66),

$$
\begin{align*}
& \int_{0}^{T}\left\{\mathbb{E}_{s}\left[f_{1}(t)-g_{1}(t)\right] \phi_{1}(s, t)+\mathbb{E}_{s}\left[D_{1, t}^{\phi}\left(f_{1}\left(t-g_{1}(t)\right)\right] B_{1}^{(H)}(s)\right.\right. \\
& \left.-\mathbb{E}_{s}\left[D_{1, s}^{\phi} D_{1, t}^{\phi}\left(f_{1}(t)-g_{1}(t)\right)\right]+\mathbb{E}_{s}\left[D_{1, t}^{\phi} f_{2}(t)\right] B_{2}^{(H)}(s)-\mathbb{E}_{s}\left[D_{2, s}^{\phi} D_{1, t}^{\phi} f_{2}(t)\right]\right\} d t=0, \tag{70}
\end{align*}
$$

where we have used the shorthand notation

$$
\mathbb{E}_{s}[\cdot]=\mathbb{E}\left[\cdot \mid \mathcal{F}_{s}^{(H)}\right] .
$$

We have proved:

Theorem 3.3 Suppose the claim $F$ represented by (58) is such that $D_{1, s}^{\phi} D_{1, t}^{\phi} f_{1}(t)$ and $D_{2, s}^{\phi} D_{1, t}^{\phi} f_{2}(t)$ exist for all $s, t \in[0, T]$. Suppose $\hat{g}_{1}(t)$ is an adapted process in $\mathcal{L}_{\phi}^{1,2}$ such that $D_{1, t}^{\phi} \hat{g}_{1}(t)$ and $D_{1, s}^{\phi} D_{1, t}^{\phi} \hat{g}_{1}(t)$ exist for all $s, t \in[0, T]$. Then the following are equivalent:
(i) $\hat{g}_{1}(t)$ is a minimal variance hedging portfolio for $F$, i.e. $\hat{g}_{1}(t)$ minimizes (60) over all adapted $g_{1}(t) \in \mathcal{L}_{\phi}^{1,2}$
(ii) $g_{1}(t)=\hat{g}_{1}(t)$ satisfies equation (70).

## MINIMAL VARIANCE HEDGING FOR FRACTIONAL BROWNIAN MOTION19

Note that the same method also applies if we assume a fractional exponential dynamics for the asset prices, which represents a more realistic financial model.
To illustrate this result we consider the following special case:
Example 3.4 Suppose $f_{1}(t)=0$ and

$$
\begin{equation*}
D_{1, t}^{\phi} f_{2}(t)=h(t), \quad \text { a deterministic function } . \tag{71}
\end{equation*}
$$

We seek a minimal variance hedging portfolio $g_{1}^{*}(t)$ for the claim

$$
\begin{equation*}
F(\omega)=\int_{0}^{T} f_{2}(t) d B_{2}^{(H)}(t) \tag{72}
\end{equation*}
$$

In this case (70) gets the form

$$
\begin{gather*}
\int_{0}^{T}\left\{-\mathbb{E}_{s}\left[g_{1}(t)\right] \phi_{1}(s, t)-\mathbb{E}_{s}\left[D_{1, t}^{\phi} g_{1}(t)\right] B_{1}^{(H)}(s)+\mathbb{E}_{s}\left[D_{1, s}^{\phi} D_{1, t}^{\phi} g_{1}(t)\right]\right. \\
\left.+h(t) B_{2}^{(H)}(s)\right\} d t=0 \quad \text { for a.a. }(s, \omega) \tag{73}
\end{gather*}
$$

Let us try to choose $g_{1}(t)$ such that

$$
\begin{equation*}
D_{1, t}^{\phi} g_{1}(t)=0 . \tag{74}
\end{equation*}
$$

Then (71) reduces to

$$
\begin{equation*}
\int_{0}^{T} \mathbb{E}_{s}\left[g_{1}(t)\right] \phi_{1}(s, t) d t=B_{2}^{(H)}(s) \int_{0}^{T} h(t) d t \tag{75}
\end{equation*}
$$

or, since $g_{1}$ is adapted,

$$
\begin{equation*}
\int_{0}^{s} g_{1}(t) \phi_{1}(s, t) d t+\int_{s}^{T} \mathbb{E}_{s}\left[g_{1}(t)\right] \phi_{1}(s, t) d t=B_{2}^{(H)}(s) \int_{0}^{T} h(t) d t, \quad s \in[0, T] . \tag{76}
\end{equation*}
$$

In particular, if we choose $s=T$ we get the equation

$$
\begin{equation*}
\int_{0}^{T} g_{1}(t) \phi_{1}(T, t) d t=B_{2}^{(H)}(T) \int_{0}^{T} h(t) d t \tag{77}
\end{equation*}
$$

which clearly has no adapted solution $g_{1}(t)$. (However, it obviously has a non-adapted solution.) Therefore an optimal portfolio $g_{1}(t)=g_{1}^{*}(t)$ for the claim (72), if it exists, cannot satisfy (74).

## References

[1] F. Biagini, Y. Hu, B. Øksendal and A. Sulem, A stochastic maximum principle for processes driven by fractional Brownian motion, Stoch. Proc. and their Appl., 100 (2002), pp. 233-253.
[2] F.Biagini, B.Øksendal, A.Sulem, N.Wallner, An introduction to White noise theory and Malliavin calculus for fractional Brownian motion Proceedings of the Royal Society of London (to appear).
[3] D. Brody, J. Syroka and M. Zervos, Pricing weather derivative options, Quantitative Finance, 2 (2002), pp. 189-198.
[4] A. Dasgupta, Fractional Brownian Motion: Its properties and applications to stochastic integration, Ph.D. Thesis, Dept. of Statistics, University of North Caroline at Chapel Hill 1997.
[5] G. Di Nunno, Stochastic integral representations, stochastic derivatives and minimal variance hedging, Stochastics and Stochastics Reports, 73 (2002), pp. 181-198.
[6] T. E. Duncan, Y. Hu and B. Pasik-Duncan, Stochastic calculus for fractional Brownian motion, I. Theory. SIAM J. Control Optim., 38 (2000), pp. 582-612.
[7] R.J. Elliott and J. van der Hoek, A general fractional white noise theory and applications to finance, Math. Finance, 13 (2003), pp. 301330.
[8] H. Föllmer and M. Schweizer, Hedging of contingent claims under incomplete information, In M.H.A. Davis and R. Elliott (eds): Applied Stochastic Analysis, Gordon and Breach 1991, pp. 389-414.
[9] Y. Hu and B. Øksendal, Fractional white noise calculus and applications to finance, Infinite dimensional analysis, quantum probability and related topics, 6:1 (2003), pp. 1-32.
[10] B. Mandelbrot, Fractals and Scaling in Finance: Discontinuity, Concentration, Risk, Springer-Verlag, 1997.
[11] B.B. Mandelbrot and J.W. van Ness, Fractional Brownian motions, fractional noises and applications, SIAM Rev., 10 (1968), pp. 422-437.
[12] R. Norvais̆A, Modelling of stock price changes. A real analysis approach, Finance and Stochastics, 4 (2000), pp. 34-369.
[13] I. Norros, E. Valkeila and J. Virtamo, An elementary approach to a Girsanov formula and other analytic results on fractional Brownian motions, Bernoulli, 5 (1999), pp. 571-587.
[14] B. Øksendal, Fractional Brownian motion in finance, Preprint, Department of Mathematics, University of Oslo 28/2003.
[15] L.C.G. Rogers, Arbitrage with fractional Brownian motion, Math. Finance, 7 (1997), pp. 95-105.
[16] D.M. Salopek, Tolerance to arbitrage, Stoch. Proc. and their Applications, 76 (1998), pp. 217-230.
[17] M. Schweizer, A guided tour through quadratic hedging approaches, In: Jouini E., Cvitanic J., Musiela M.(eds) Option pricing, interest rates and risk management.Cambridge, UK:Cambridge University Press 2001a, pp. 538-574.
[18] A. Shiryaev, Essentials of Stochastic Finance, World Scientific, 1999.
[19] A. Shiryaev, On arbitrage and replication for fractal models, In A. Shiryaev and A. Sulem (eds.): Workshop on Mathematical Finance, INRIA, Paris, 1998.
[20] I. Simonsen, Anti-correlations in the Nordic electricity spot market, Manuscript, NORDITA Copenhagen, May 2001.
[21] N. Wallner, Fractional Brownian Motion and Applications to Finance, Thesis, Philipps-Universität Marburg, March 2001.


[^0]:    *Received January 28, 2003; accepted for publication August 13, 2003.
    ${ }^{\dagger}$ Department of Mathematics, University of Bologna, Piazza di Porta S. Donato, 5, I-40127 Bologna, Italy (biagini@dm.unibo.it).
    $\ddagger$ Department of Mathematics, University of Oslo, Box 1053 Blindern, N-0316 Oslo, Norway
    (oksendal@math.uio.no); Norwegian School of Economics and Business Administration, Helleveien 30, N-5045 Bergen, Norway.

